CS162 Operating Systems and Systems Programming Lecture 25

Distributed 2: Distributed Decision Making (Con't), RPC, and Distributed Storage

April 25th, 2024 Prof. John Kubiatowicz http://cs162.eecs.Berkeley.edu

Recall: Two-Phase Commit Protocol (2PC)

- Prepare Phase:
 - The global coordinator requests that all participants will promise to commit or rollback the transaction
 - Participants record promise in log, then acknowledge
 - If anyone votes to abort, coordinator writes "Abort" in its log and tells everyone to abort; each records "Abort" in log
- · Commit Phase:
 - After all participants respond that they are prepared, then the coordinator writes "Commit" to its log
 - Then asks all nodes to commit: they respond with ACK
 - After receive ACKs, coordinator writes "Got Commit" to log
- Persistent stable log on each machine: keep track of whether commit has happened
 - Required for good semantics
 - If a machine crashes, when it wakes up it first checks its log to recover state of world at time of crash

Recall: Distributed Consensus Making

- · Consensus problem
 - All nodes propose a value
 - Some nodes might crash and stop responding
 - Eventually, all remaining nodes decide on the same value from set of proposed values
- · Distributed Decision Making
 - Choose between "true" and "false"
 - Or Choose between "commit" and "abort"
- Equally important (but often forgotten!): make it durable!
 - How do we make sure that decisions cannot be forgotten?
 - » This is the "D" of "ACID" in a regular database
 - In a global-scale system?
 - » What about erasure coding or massive replication?
 - » Like BlockChain applications!

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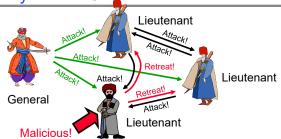
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Alternatives to 2PC

- Three-Phase Commit: One more phase, allows nodes to fail or block and still make progress.
- PAXOS: An alternative used by Google and others that does not have 2PC blocking problem
 - Develop by Leslie Lamport (Turing Award Winner)
 - No fixed leader, can choose new leader on fly, deal with failure
 - Some think this is extremely complex!
- RAFT: PAXOS alternative from John Osterhout (Stanford)
 - Simpler to describe complete protocol
- What happens if one or more of the nodes is malicious?
 - Malicious: attempting to compromise the decision making
 - Use a more hardened decision making process:
 Byzantine Agreement and Block Chains

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Byzantine General's Problem

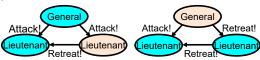


- Byazantine General's Problem (n players):
 - One General and n-1 Lieutenants
 - Some number of these (f) can be insane or malicious
- The commanding general must send an order to his n-1 lieutenants such that the following Integrity Constraints apply:
 - IC1: All loyal lieutenants obey the same order
 - IC2: If the commanding general is loyal, then all loyal lieutenants obey the order he

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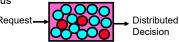
Byzantine General's Problem (con't)

- · Impossibility Results:
 - Cannot solve Byzantine General's Problem with n=3 because one malicious player can mess up things



- With f faults, need n > 3f to solve problem
- · Various algorithms exist to solve problem
 - Original algorithm has #messages exponential in n
 - Newer algorithms have message complexity O(n²)
 - » One from MIT, for instance (Castro and Liskov, 1999)
- Use of BFT (Byzantine Fault Tolerance) algorithm
 - Allow multiple machines to make a coordinated decision even if some subset of them (< n/3) are malicious

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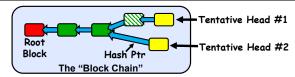


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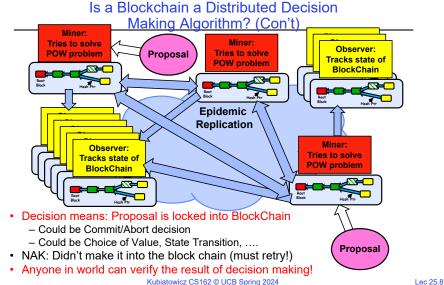
Is a BlockChain a Distributed Decision Making Algorithm?



- · BlockChain: a chain of blocks connected by hashes to root block
 - The Hash Pointers are unforgeable (assumption)
 - The Chain has no branches except perhaps for heads
 - Blocks are considered "authentic" part of chain when they have authenticity info in them
- · How is the head chosen?
 - Some consensus algorithm
 - In many BlockChain algorithms (e.g. BitCoin, Ethereum), the head is chosen by solving hard problem
 - » This is the job of "miners" who try to find "nonce" info that makes hash over block have specified number of zero bits in it
 - » The result is a "Proof of Work" (POW)
 - » Selected blocks above (green) have POW in them and can be included in chains

Longest chain wins

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Recall: Distributed Applications Build With Messages

- How do you actually program a distributed application?
 - Need to synchronize multiple threads, running on different machines
 - » No shared memory, so cannot use test&set



- One Abstraction: send/receive messages
 - » Already atomic: no receiver gets portion of a message and two receivers cannot get same message
- Interface:

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- Mailbox (mbox): temporary holding area for messages
 - » Includes both destination location and queue
 - » Over Internet, destination specified by IP address and Port (Recall Web server example!)
- Send(message.mbox)
 - » Send message to remote mailbox identified by mbox
- Receive(buffer, mbox)
 - » Wait until mbox has message, copy into buffer, and return
 - » If threads sleeping on this mbox, wake up one of them

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How do we know that both sides speak same language?

- An object in memory has a machine-specific binary representation
 - Threads within a single process have the same view of what's in memory
 - Easy to compute offsets into fields, follow pointers, etc.
- In the absence of shared memory, externalizing an object requires us to turn it into a sequential sequence of bytes
 - Serialization/Marshalling: Express an object as a sequence of bytes
 - Deserialization/Unmarshalling: Reconstructing the original object from its marshalled form at destination

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Simple Data Types

uint32_t x;

- Suppose I want to write a x to a file
- First, open the file: FILE* f = fopen("foo.txt", "w");
- · Then, I have two choices:
 - 1. fprintf(f, "%lu", x);
 - 2. fwrite(&x, sizeof(uint32 t), 1, f);
 - » Or equivalently, write(fd, &x, sizeof(uint32 t)); (perhaps with a loop to be safe)
- · Neither one is "wrong" but sender and receiver should be consistent!

Machine Representation

- · Consider using the machine representation:
 - fwrite(&x, sizeof(uint32 t), 1, f);
- How do we know if the recipient represents x in the same way?
 - For pipes, is this a problem?
 - What about for sockets?

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Endianness

- For a byte-address machine, which end of a machinerecognized object (e.g., int) does its byte-address refer to?
- Big Endian: address points to most-significant byte
- · Little Endian: address points to least-significant byte

```
int main(int argc, char *argv[])
{
    int val = 0x12345678;
    int i;
    printf("val = %x\n", val);
    for (i = 0; i < sizeof(val); i++) {
        printf("val[%d] = %x\n", i, ((uint8_t *) &val)[i]);
    }
}</pre>
Alpha
ARM
IIA-64 (64 b)
MIPS
```

Intel x86 64 (64 bit) Little Endian

Endianness

Big Endian

Big Endian

Big Endian

Big Endian

Little Endian

Processor

Sun Sparc

IBM S/390

Motorola 68000

PowerPC (PPC)

Intel x86 (32 bit)

Result: val[0] = 78 val[1] = 56

val[1] = 56
val[2] = 34
val[3] = 12

val = 12345678

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What Endian is the Internet?

```
NAME
        arpa/inet.h - definitions for internet operations
 SYNOPSIS
  DESCRIPTION
        The in_port_t and in_addr_t types shall be defined as described in <netinet/in.h>.
       The in_addr structure shall be defined as described in <netinet/in.h>.
        The INET_ADDRSTRLEN <sup>[IP6]</sup> 

and INET6_ADDRSTRLEN 

macros shall be defined as described in <netinet/in.h.
        The following shall either be declared as functions, defined as macros, or both, If functions are declared, function prototype
        uint32 t htonl(uint32 t);
        uint16_t htons(uint16_t);
       uint32_t ntohl(uint32_t);
uint16_t ntohs(uint16_t);
        The uint32_t and uint16_t types shall be defined as described in <inttypes.h:
        The following shall be declared as functions and may also be defined as macros. Function prototypes shall be provided
                       inet addr(const char *):
        in addr t
                        *inet_ntoa(struct in_addr);
       const char *inet_ntop(int, const void *restrict, char *restrict,
                         inet_pton(int, const char *restrict, void *restrict);
        Inclusion of the <arpa/inet.h> header may also make visible all symbols from <netinet/in.h> and <inttypes.h>
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```

- Big Endian
 - Network byte order
 - · Vs. "host byte order"

Dealing with Endianness

· Decide on an "on-wire" endianness

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- Convert from native endianness to "on-wire" endianness before sending out data (serialization/marshalling)
 - uint32_t htonl(uint32_t) and uint16_t htons(uint16_t) convert from native endianness to network endianness (big endian)
- Convert from "on-wire" endianness to native endianness when receiving data (deserialization/unmarshalling)
 - uint32_t ntohl(uint32_t) and uint16_t ntohs(uint16_t) convert from network endianness to native endianness (big endian)

What About Richer Objects?

- Consider word_count_t of Homework 0 and 1 ...
- · Each element contains:
 - An int
 - A pointer to a string (of some length)
 - A pointer to the next element
- fprintf_words writes these as a sequence of lines (character strings with \n) to a file stream
- What if you wanted to write the whole list as a binary object (and read it back as one)?
 - How do you represent the string?
 - Does it make any sense to write the pointer?

typedef struct word_count
{
 char *word;
 int count;
 struct word_count *next;
}
word_count_t;

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Data Serialization Formats

- · JSON and XML are commonly used in web applications
- · Lots of ad-hoc formats

```
INDOTYPE glosasry PUBLIC "-//OASIS/PDD DoBook V3.1//EN">

«glosasry-ttile-bemaple glosasry-ftitle>

«glosable>*ttile>Set/tile>

«glosable>*ttile>Set/tile>

«glosable>*ttile>Set/tile>

«glosabley* In-"SOKU" Sortha-"SOKU">

«glosablety In-"SOKU" Sortha-"SOKU">

«glosablety In-"SOKU" Sortha-"SOKU">

«glosablety In-"SOKU-" Sortha-"SOKU-">

«Ancronym=SOKU-*/Ancronym>

«Ancronym=SOKU-*/Ancronym>

«Ancronym=SOKU-*/Ancronym>

«hobrev=108 887911886*/Abneva-"

«glosable*>

«para*A meta-markup language, used to create markup languages such as DocBook.*/para>

«glosaseAlso OtherTerm="MKL">

«glosasseAlso OtherTerm="MKL">

«Glosable*>

«Glosable**

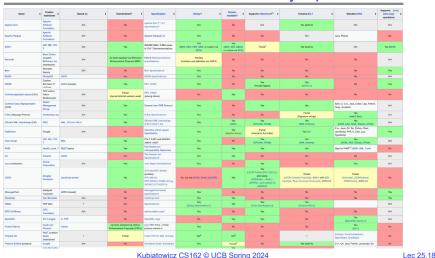
«Glosable**
```

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Administrivia

- Midterm 3: This Thursday!
 - No class on Thursday. I'll have special office hours during class time.
 - Three double-sided pages of notes
 - Watch for Ed post about where you should go: we have multiple exam rooms
- All material up to today's lecture is fair game
- Final deadlines during RRR week:
 - Yes, there will be office hours watch for specifics
- Also we have a special lecture (just for fun) next Tuesday
 - During normal class time!

Data Serialization Formats: Many Options



Administrivia (Con't)

```
    You need to know your units as CS/Engineering students!
```

```
• Units of Time: "s": Second, "min": 60s, "h": 3600s, (of course)
```

```
- Millisecond: 1\text{ms} \Rightarrow 10^{-3} \text{ s}

- Microsecond: 1\mu\text{s} \Rightarrow 10^{-6} \text{ s}

- Nanosecond: 1\text{ns} \Rightarrow 10^{-9} \text{ s}
```

- Picosecond: 1ps \Rightarrow 10⁻¹² s

Integer Sizes: "b" ⇒ "bit", "B" ⇒ "byte" == 8 bits, "W"⇒"word"==? (depends. Could be 16b, 32b, 64b)

· Units of Space (memory), sometimes called the "binary system"

```
- Kilo: 1\text{KB} = 1\text{KiB} ⇒ 1024 bytes == 2^{10} bytes == 1.024 \approx 1.0 \times 10^3

- Mega: 1\text{MB} = 1\text{MiB} ⇒ (1024)^2 bytes == 2^{20} bytes == 1.048,576 \approx 1.0 \times 10^6

- Giga: 1\text{GB} = 1\text{GiB} ⇒ (1024)^3 bytes == 2^{30} bytes == 1.073,741,824 \approx 1.1 \times 10^9

- Tera: 1\text{TB} = 1\text{TiB} ⇒ (1024)^4 bytes == 2^{40} bytes == 1.099,511,627,776 \approx 1.1 \times 10^{12}

- Peta: 1\text{PB} = 1\text{PiB} ⇒ (1024)^6 bytes == 2^{50} bytes == 1.125,899,906,842,624 \approx 1.1 \times 10^{15}

- Exa: 1\text{EB} = 1\text{EiB} ⇒ (1024)^6 bytes == 2^{60} bytes == 1.152,921,504,606,846,976 \approx 1.2 \times 10^{18}
```

· Units of Bandwidth, Space on disk/etc, Everything else..., sometimes called the "decimal system"

```
- Kilo: 1KB/s \Rightarrow 10^3 bytes/s, 1KB \Rightarrow 10^3 bytes

- Mega: 1MB/s \Rightarrow 10^6 bytes/s, 1MB \Rightarrow 10^6 bytes

- Giga: 1GB/s \Rightarrow 10^9 bytes/s, 1GB \Rightarrow 10^9 bytes

- Tera: 1TB/s \Rightarrow 10^{12} bytes/s, 1TB \Rightarrow 10^{12} bytes

- Peta: 1PB/s \Rightarrow 10^{15} bytes/s, 1PB \Rightarrow 10^{15} bytes

- Exa: 1EB/s \Rightarrow 10^{18} bytes/s, 1EB \Rightarrow 10^{18} bytes
```

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Remote Procedure Call (RPC)

- · Raw messaging is a bit too low-level for programming
 - Must wrap up information into message at source
 - Must decide what to do with message at destination
 - May need to sit and wait for multiple messages to arrive
 - And must deal with machine representation by hand
- Another option: Remote Procedure Call (RPC)
 - Calls a procedure on a remote machine
 - Idea: Make communication look like an ordinary function call
 - Automate all of the complexity of translating between representations
 - Client calls

remoteFileSystem→Read("rutabaga");

- Translated automatically into call on server:

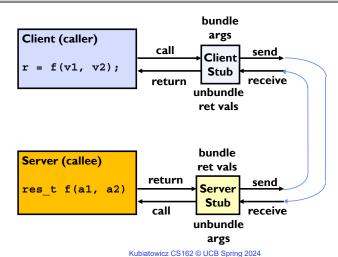
fileSys -> Read("rutabaga");

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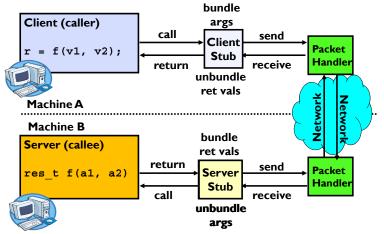
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RPC Concept



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RPC Information Flow



RPC Implementation

- · Request-response message passing (under covers!)
- "Stub" provides glue on client/server
 - Client stub is responsible for "marshalling" arguments and "unmarshalling" the return values
 - Server-side stub is responsible for "unmarshalling" arguments and "marshalling" the return values.
- Marshalling involves (depending on system)
 - Converting values to a canonical form, serializing objects, copying arguments passed by reference, etc.
 - Use of standardized serialization protocol

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RPC Details (1/3)

- · Equivalence with regular procedure call
 - Parameters ⇔ Request Message
 - Result ⇔ Reply message
 - Name of Procedure: Passed in request message
 - Return Address: mbox2 (client return mail box)
- Stub generator: Compiler that generates stubs
 - Input: interface definitions in an "interface definition language (IDL)"
 - » Contains, among other things, types of arguments/return
 - Output: stub code in the appropriate source language
 - » Code for client to pack message, send it off, wait for result, unpack result and return to caller
 - » Code for server to unpack message, call procedure, pack results, send them off

RPC Details (2/3)

- · Cross-platform issues:
 - What if client/server machines are different architectures/ languages?
 - » Convert everything to/from some canonical form
 - » Tag every item with an indication of how it is encoded (avoids unnecessary conversions)
- How does client know which mbox (destination queue) to send to?
 - Need to translate name of remote service into network endpoint (Remote machine, port, possibly other info)
 - Binding: the process of converting a user-visible name into a network endpoint

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- » This is another word for "naming" at network level
- » Static: fixed at compile time
- » Dynamic: performed at runtime

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RPC Details (3/3)

- Dynamic Binding
 - Most RPC systems use dynamic binding via name service
 - » Name service provides dynamic translation of service → mbox
 - Why dynamic binding?
 - » Access control: check who is permitted to access service
 - » Fail-over: If server fails, use a different one
- What if there are multiple servers?
 - Could give flexibility at binding time
 - » Choose unloaded server for each new client
 - Could provide same mbox (router level redirect)
 - » Choose unloaded server for each new request
 - » Only works if no state carried from one call to next
- · What if multiple clients?
 - Pass pointer to client-specific return mbox in request

Problems with RPC: Non-Atomic Failures

- · Different failure modes in dist. system than on a single machine
- Consider many different types of failures
 - -User-level bug causes address space to crash
 - Machine failure, kernel bug causes all processes on same machine to fail
 - -Some machine is compromised by malicious party
- Before RPC: whole system would crash/die
- After RPC: One machine crashes/compromised while others keep working
- Can easily result in inconsistent view of the world
 - -Did my cached data get written back or not?
 - -Did server do what I requested or not?
- Answer? Distributed transactions/Byzantine Commit

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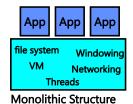
Problems with RPC: Performance

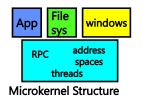
- RPC is not performance transparent:
 - Cost of Procedure call « same-machine RPC « network RPC
 - Overheads: Marshalling, Stubs, Kernel-Crossing, Communication
- · Programmers must be aware that RPC is not free
 - Caching can help, but may make failure handling complex

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Microkernel operating systems

- Example: split kernel into application-level servers.
 - File system looks remote, even though on same machine





- Why split the OS into separate domains?
 - Fault isolation: bugs are more isolated (build a firewall)
 - Enforces modularity: allows incremental upgrades of pieces of software (client or server)
 - Location transparent: service can be local or remote
 - » For example in the X windowing system: Each X client can be on a separate machine from X server; Neither has to run on the machine with the frame buffer.

Cross-Domain Communication/Location Transparency

- How do address spaces communicate with one another?
 - Shared Memory with Semaphores, monitors, etc...
 - File System

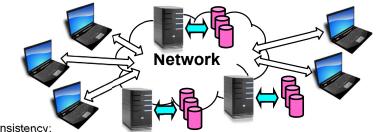
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- Pipes (1-way communication)
- "Remote" procedure call (2-way communication)
- RPC's can be used to communicate between address spaces on different machines or the same machine
 - Services can be run wherever it's most appropriate
 - Access to local and remote services looks the same
- · Examples of RPC systems:
 - CORBA (Common Object Request Broker Architecture)
 - DCOM (Distributed COM)
 - RMI (Java Remote Method Invocation)

Network-Attached Storage and the CAP Theorem

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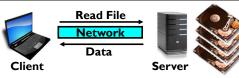
- · Consistency:
 - Changes appear to everyone in the same serial order
- Availability:

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- Can get a result at any time
- Partition-Tolerance
 - System continues to work even when network becomes partitioned
- Consistency, Availability, Partition-Tolerance (CAP) Theorem: Cannot have all three at same time
 - Otherwise known as "Brewer's Theorem" Kubiatowicz CS162 © UCB Spring 2024

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Distributed File Systems



- Transparent access to files stored on a remote disk
- · Mount remote files into your local file system
 - Directory in local file system refers to remote files
 - e.g., /users/jane/prog/foo.c on laptop actually refers to /prog/foo.c on adj.cs.berkeley.edu
- Naming Choices:

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- [Hostname,localname]: Filename includes server
 - » No location or migration transparency, except through DNS remapping
- A global name space: Filename unique in "world"
 - » Can be served by any server

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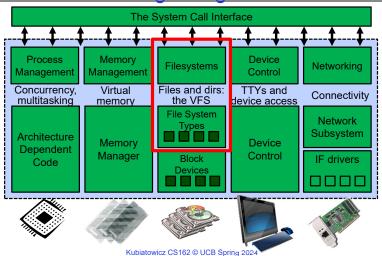
mount adj:/jane coeus:/sue

mount

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Enabling Design: VFS



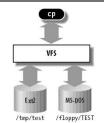
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Recall: Layers of I/O...



```
length = read(input fd, buffer, BUFFER SIZE);
   ssize_t read(int, void *, size_t) {
    marshal args into registers
    issue syscall
    register result of syscall to rtn value
    Exception U→K, interrupt processing
    void syscall_handler (struct intr_frame *f) {
       unmarshall call#, args from regs
       dispatch : handlers[call#](args)
       marshal results fo syscall ret
     ssize_t vfs_read(struct file *file, char __user *buf,
                       size t count, loff t *pos) {
        User Process/File System relationship
        call device driver to do the work
                                          Device Driver
```

Virtual Filesystem Switch

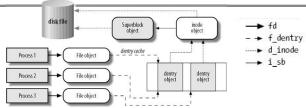


```
inf = open("/floppy/TEST", O_RDONLY, 0);
i = read(inf, buf, 4096);
  write(outf, buf, i);
```

- VFS: Virtual abstraction similar to local file system.
 - Provides virtual superblocks, inodes, files, etc
 - Compatible with a variety of local and remote file systems » provides object-oriented way of implementing file systems
- · VFS allows the same system call interface (the API) to be used for different types of file systems
 - The API is to the VFS interface, rather than any specific type of file system

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VES Common File Model in Linux

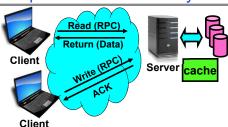


- · Four primary object types for VFS:
 - superblock object: represents a specific mounted filesystem
 - inode object: represents a specific file
 - dentry object: represents a directory entry
 - file object: represents open file associated with process
- There is no specific directory object (VFS treats directories as files)
- · May need to fit the model by faking it
 - Example: make it look like directories are files
 - Example: make it look like have inodes, superblocks, etc.

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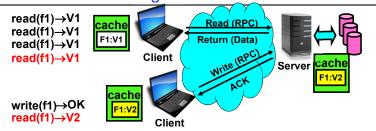
Simple Distributed File System



- · Remote Disk: Reads and writes forwarded to server
 - Use Remote Procedure Calls (RPC) to translate file system calls into remote requests
 - No local caching, but can be cache at server-side
- Advantage: Server provides consistent view of file system to multiple clients
- · Problems? Performance!
 - Going over network is slower than going to local memory
 - Lots of network traffic/not well pipelined
 - Server can be a bottleneck

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Use of caching to reduce network load



- · Idea: Use caching to reduce network load
 - In practice: use buffer cache at source and destination
- Advantage: if open/read/write/close can be done locally, don't need to do any network traffic...fast!
- · Problems:

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- Failure:
 - » Client caches have data not committed at server
- Cache consistency!
 - » Client caches not consistent with server/each other

 What if server crashes? Can client wait until it comes back and just continue making requests?

Dealing with Failures

- Changes in server's cache but not in disk are lost
- · What if there is shared state across RPC's?
 - Client opens file, then does a seek
 - Server crashes
 - What if client wants to do another read?
- Similar problem: What if client removes a file but server crashes before acknowledgement?

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Stateless Protocol

- Stateless Protocol: A protocol in which all information required to service a request is included with the request
- Even better: Idempotent Operations repeating an operation multiple times is same as executing it just once (e.g., storing to a mem addr.)
- Client: timeout expires without reply, just run the operation again (safe regardless of first attempt)
- · Recall HTTP: Also a stateless protocol
 - Include cookies with request to simulate a session

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NFS Continued

- NFS servers are stateless; each request provides all arguments require for execution
 - E.g. reads include information for entire operation, such as ReadAt(inumber, position), not Read(openfile)
 - No need to perform network open() or close() on file each operation stands on its own
- Idempotent: Performing requests multiple times has same effect as performing them exactly once
 - Example: Server crashes between disk I/O and message send, client resend read, server does operation again
 - Example: Read and write file blocks: just re-read or re-write file block no other side effects
 - Example: What about "remove"? NFS does operation twice and second time returns an advisory error
- Failure Model: Transparent to client system
 - Is this a good idea? What if you are in the middle of reading a file and server crashes?
 - Options (NFS Provides both):
 - » Hang until server comes back up (next week?)
 - » Return an error. (Of course, most applications don't know they are talking over network)

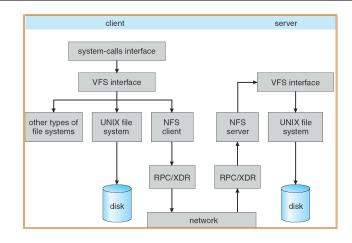
Case Study: Network File System (NFS)

- Three Layers for NFS system
 - UNIX file-system interface: open, read, write, close calls + file descriptors
 - VFS layer: distinguishes local from remote files
 - » Calls the NFS protocol procedures for remote requests
 - NFS service layer: bottom layer of the architecture
 - » Implements the NFS protocol
- NFS Protocol: RPC for file operations on server
 - XDR Serialization standard for data format independence
 - Reading/searching a directory
 - manipulating links and directories
 - accessing file attributes/reading and writing files
- Write-through caching: Modified data committed to server's disk before results are returned to the client
 - lose some of the advantages of caching
 - time to perform write() can be long
 - Need some mechanism for readers to eventually notice changes! (more on this later)

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NFS Architecture



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NFS Cache consistency

- · NFS protocol: weak consistency
 - Client polls server periodically to check for changes
 - » Polls server if data hasn't been checked in last 3-30 seconds (exact timeout is tunable parameter).
 - » Thus, when file is changed on one client, server is notified, but other clients use old version of file until timeout.



- What if multiple clients write to same file?
 - » In NFS, can get either version (or parts of both)
 - » Completely arbitrary!

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Sequential Ordering Constraints

- · What sort of cache coherence might we expect?
 - i.e. what if one CPU changes file, and before it's done, another CPU reads file?
- Example: Start with file contents = "A"

Client 1: Read: gets A | Write B | Read: parts of B or C

Time

- · What would we actually want?
 - Assume we want distributed system to behave exactly the same as if all processes are running on single system
 - » If read finishes before write starts, get old copy
 - » If read starts after write finishes, get new copy
 - » Otherwise, get either new or old copy
 - For NFS:
 - » If read starts more than 30 seconds after write, get new copy; otherwise, could get partial update

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NFS Pros and Cons

NFS Pros:

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- Simple, Highly portable
- · NFS Cons:
 - Sometimes inconsistent!
 - Doesn't scale to large # clients
 - » Must keep checking to see if caches out of date
 - » Server becomes bottleneck due to polling traffic

Andrew File System

- Andrew File System (AFS, late 80's) → DCE DFS (commercial product)
- · Callbacks: Server records who has copy of file
 - On changes, server immediately tells all with old copy
 - No polling bandwidth (continuous checking) needed
- · Write through on close
 - Changes not propagated to server until close()
 - Session semantics: updates visible to other clients only after the file is closed
 - » As a result, do not get partial writes: all or nothing!
 - » Although, for processes on local machine, updates visible immediately to other programs who have file open
- In AFS, everyone who has file open sees old version
 - Don't get newer versions until reopen file

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Andrew File System (con't)

- Data cached on local disk of client as well as memory
 - On open with a cache miss (file not on local disk):
 - » Get file from server, set up callback with server
 - On write followed by close:
 - » Send copy to server; tells all clients with copies to fetch new version from server on next open (using callbacks)
- What if server crashes? Lose all callback state!
 - Reconstruct callback information from client: go ask everyone "who has which files cached?"
- · AFS Pro: Relative to NFS, less server load:
 - Disk as cache ⇒ more files can be cached locally
 - Callbacks ⇒ server not involved if file is read-only
- For both AFS and NFS: central server is bottleneck!
 - Performance: all writes→server, cache misses→server
 - Availability: Server is single point of failure
 - Cost: server machine's high cost relative to workstation

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Summary (2/2)

- Transparent access to files stored on a remote disk
- Caching for performance
- - file systems
- Cache Consistency: Keeping client caches consistent with one another
 - If multiple clients, some reading and some writing, how do stale cached copies get updated?
 - NFS: check periodically for changes
 - AFS: clients register callbacks to be notified by server of changes

Summary (1/2)

- Byzantine General's Problem: distributed decision making with malicious failures
 - One general, n-1 lieutenants: some number of them may be malicious (often "f" of them)
 - All non-malicious lieutenants must come to same decision
 - If general not malicious, lieutenants must follow general
 - Only solvable if n ≥ 3f+1
- BlockChain protocols:
 - Cryptographically-driven ordering protocol
 - Could be used for distributed decision making
- Remote Procedure Call (RPC): Call procedure on remote machine or in remote domain
 - Provides same interface as procedure
 - Automatic packing and unpacking of arguments without user programming (in stub)
 - Adapts automatically to different hardware and software architectures at remote end

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- · Distributed File System:
- VFS: Virtual File System layer (Or Virtual Filesystem Switch)
 - Provides mechanism which gives same system call interface for different types of

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