# CS162 Operating Systems and Systems Programming Lecture 3

Abstractions 1: Threads and Processes A quick, programmer's viewpoint

January 23<sup>rd</sup>, 2024 Prof. John Kubiatowicz http://cs162.eecs.Berkeley.edu

# Goals for Today: The Thread Abstraction

- · What threads are
  - And what they are not
- Why threads are useful (motivation)
- · How to write a program using threads
- Alternatives to using threads



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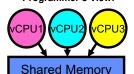
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#### Recall: Four Fundamental OS Concepts

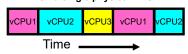
- Thread: Execution Context
  - Fully describes program state
  - Program Counter, Registers, Execution Flags, Stack
- Address space (with or w/o translation)
  - Set of memory addresses accessible to program (for read or write)
  - May be distinct from memory space of the physical machine (in which case programs operate in a virtual address space)
- · Process: an instance of a running program
  - Protected Address Space + One or more Threads
- Dual mode operation / Protection
  - Only the "system" has the ability to access certain resources
  - Combined with translation, isolates programs from each other and the OS from programs

# Recall: Illusion of Multiple Processors

#### Programmer's View:



On a single physical CPU



- Threads are virtual cores
- Multiple threads: Multiplex hardware in time
- A Thread is <u>executing</u> on a processor when it is resident in that processor's registers
- Each virtual core (thread) has:
  - Program counter (PC), stack pointer (SP)
  - Registers both integer and floating point
- Where is "it" (the thread)?
  - On the real (physical) core, or
  - Saved in chunk of memory called the *Thread Control Block (TCB)*

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#### Recall: Process

- · Definition: execution environment with Restricted Rights
  - One or more threads in a (protected) Address Space
  - Owns memory (address space), file descriptors, network connections, ...
- Instance of a running program
  - When you run an executable, it runs in its own process
  - Application: one or more processes working together
- · Why processes?
  - Protected from each other!
  - OS Protected from them
- In modern OS, anything that runs outside of the kernel runs in a process

registers registers stack stack thread

Multi-Threaded Process

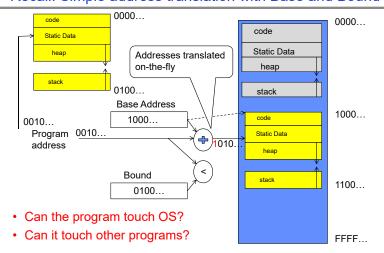
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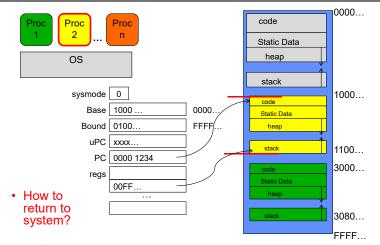
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#### Recall: Simple address translation with Base and Bound

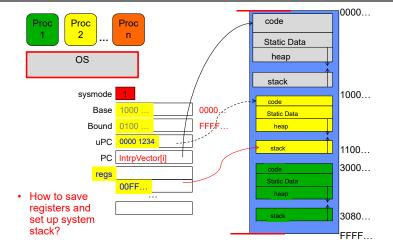


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# Simple B&B: User => Kernel

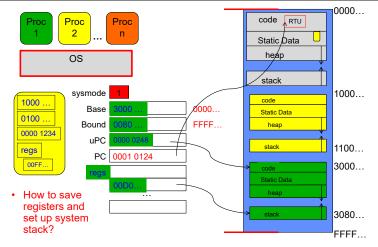


# Simple B&B: Interrupt

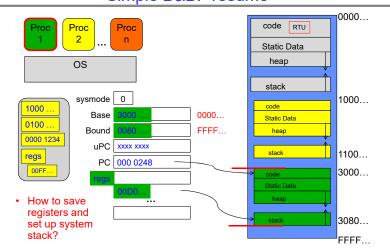


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#### Simple B&B: Switch User Process



Simple B&B: "resume"

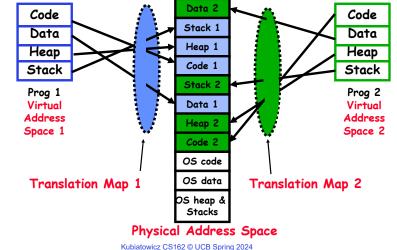


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# Is Simple Base and Bound Enough for General Systems?

- NO: Too simplistic for real systems
- · Inflexible/Wasteful:
  - Must dedicate physical memory for potential future use
  - (Think stack and heap!)
- · Fragmentation:
  - Kernel has to somehow fit whole processes into contiguous block of memory
  - After a while, memory becomes fragmented!
- Sharing:
  - Very hard to share any data between Processes or between Process and Kernel
  - Need to communicate indirectly through the kernel...

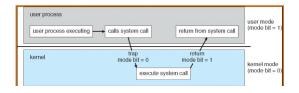
# Better: Translation through Page Table (More soon!)



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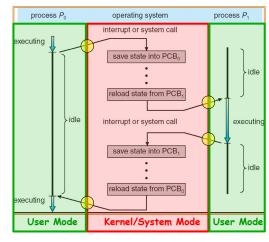
#### **Recall: Dual Mode Operation**

- Processes (i.e., programs you run) execute in user mode
  - To perform privileged actions, processes request services from the OS kernel
  - Carefully controlled transition from user to kernel mode
- Kernel executes in kernel mode
  - Performs privileged actions to support running processes
  - ... and configures hardware to properly protect them (e.g., address translation)
- · Carefully controlled transitions between user mode and kernel mode
  - System calls, interrupts, exceptions



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# Adding Protection: CPU Switch From Process A to Process B



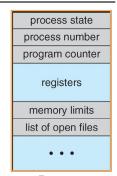
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# **Running Many Programs**

- We have the basic mechanism to:
  - switch between user processes and the kernel,
  - the kernel can switch among user processes,
  - Protect OS from user processes and processes from each other
- · Questions:
  - How do we represent user processes in the OS?
  - How do we decide which user process to run?
  - How do we pack up the process and set it aside?
  - How do we get a stack and heap for the kernel?
  - Aren't we wasting are lot of memory?

## Multiplexing Processes: The Process Control Block

- Kernel represents each process with a process control block (PCB)
  - Status (running, ready, blocked, ...)
  - Register state (when not ready)
  - Process ID (PID), User, Executable, Priority, ...
  - Execution time, ...
  - Memory space, translation, ...
- Kernel Scheduler maintains a data structure containing the PCBs
  - Give out CPU to different processes
  - This is a Policy Decision
- · Give out non-CPU resources
  - Memory/IO
  - Another policy decision



Process Control Block

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#### Scheduler

```
if ( readyProcesses(PCBs) ) {
    nextPCB = selectProcess(PCBs);
    run( nextPCB );
} else {
    run_idle_process();
}
```

- Scheduling: Mechanism for deciding which processes/threads receive hardware CPU time, when, and for how long
- · Lots of different scheduling policies provide ...
  - Fairness or

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- Realtime guarantees or
- Latency optimization or ..

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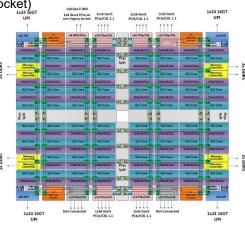
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#### Also Recall: The World Is Parallel: Saphire Rapids (2023)

• Up to 60 cores, 120 threads/package (socket)

- Up to 4 "chiplets" bonded together

- Network:
  - On-chip Mesh Interconnect
  - Fast off-chip network (UPI): directly connects 8-chips
  - 480 cores/shared memory domain!
- · Each Core Has:
  - -80 KB L1 Cache
  - -2 MB L2 Cache
  - Fraction of up to 112.5 MB L3 Cache
- DRAM/chips
  - Up to 4 TiB of DDR5 memory
- Many Accellerators of different types
  - Graphics, Encryption, AI, Security

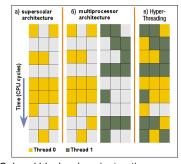


Saphire Rapids 4-chiplet single package

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# Simultaneous MultiThreading/Hyperthreading

- · Hardware scheduling technique
  - Avoids software overhead of multiplexing
  - Superscalar processors can execute multiple instructions that are independent.
  - Hyperthreading duplicates register state to make a second "thread," allowing more instructions to run.
- Can schedule each thread as if were separate CPU
  - But, sub-linear speedup!



Colored blocks show instructions executed

- · Original technique called "Simultaneous Multithreading"
  - http://www.cs.washington.edu/research/smt/index.html
  - SPARC, Pentium 4/Xeon ("Hyperthreading"), Power 5

# Administrivia: Getting started!

- Kubiatowicz Office Hours:
  - Tuesday/Thursday 3-4pm, in 673 Soda Hall
- Homework 0: Due Tomorrow!
  - Get familiar with the cs162 tools
  - configure your VM, submit via git
  - Practice finding out information:
    - » How to use GDB? How to understand output of unix tools?
    - » We don't assume that you already know everything!
    - » Learn to use "man" (command line), "help" (in gdb, etc), google
- Project 0: Started Yesterday!
  - Learn about Pintos and how to modify and debug kernel
  - Important for getting started on projects!
- Should be going to sections now Important information there
  - Any section will do until groups assigned

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## Administrivia (Con't)

- THIS Friday is Drop Deadline! HARD TO DROP LATER!
  - If you know you are going to drop, do so now to leave room for others on waitlist!
  - Why do we do this? So that groups aren't left without members!
- Group sign up via autograder form next week
  - Get finding groups of 4 people ASAP
  - Priority for same section; if cannot make this work, keep same TA
  - Remember: Your TA needs to see you in section!
- Midterm 1: 2/15
  - 8-10PM in person
  - We will say more about material when we get closer...
- Midterm 1 conflicts
  - We will handle these conflicts after have final class roster
  - Watch for queries by HeadTA to collect information

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# More About Threads: What are they?

- Definition from before: A single unique execution context
  - Describes its representation
- It provides the abstraction of: A single execution sequence that represents a separately schedulable task
  - Also a valid definition!
- Threads are a mechanism for *concurrency* (overlapping execution)
  - However, they can also run in *parallel* (simultaneous execution)
- Protection is an orthogonal concept
  - A protection domain can contain one thread or many

# **CS 162 Collaboration Policy**



Explaining a concept to someone in another group Discussing algorithms/testing strategies with other groups Discussing debugging approaches with other groups Searching online for generic algorithms (e.g., hash table)



Sharing code or test cases with another group or individual (including HW!)
Copying OR reading another group's code or test cases
Copying OR reading online code or test cases from prior years
Helping someone in another group to debug their code

- We compare all project and HW submissions against prior year submissions and online solutions and will take actions (described on the course overview page) against offenders
- Don't put a friend in a bad position by asking for help that they shouldn't give!

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#### **Motivation for Threads**

I made this term up!

- Operating systems must handle multiple things at once (MTAO)
  - Processes, interrupts, background system maintenance
- · Networked servers must handle MTAO
  - Multiple connections handled simultaneously
- Parallel programs must handle MTAO
  - To achieve better performance
- Programs with user interface often must handle MTAO
  - To achieve user responsiveness while doing computation
- Network and disk bound programs must handle MTAO
  - To hide network/disk latency
  - Sequence steps in access or communication

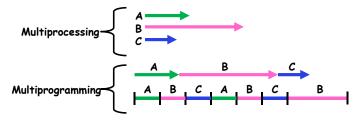
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# **Threads Allow Handling MTAO**

- Threads are a unit of concurrency provided by the OS
- Each thread can represent one thing or one task

# Multiprocessing vs. Multiprogramming

- · Some Definitions:
  - Multiprocessing: Multiple CPUs(cores)
  - Multiprogramming: Multiple jobs/processes
  - Multithreading: Multiple threads/processes
- · What does it mean to run two threads concurrently?
  - Scheduler is free to run threads in any order and interleaving
  - Thread may run to completion or time-slice in big chunks or small chunks



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# Concurrency is not Parallelism

- Concurrency is about handling multiple things at once (MTAO)
- Parallelism is about doing multiple things simultaneously
- Example: Two threads on a single-core system...
  - ... execute concurrently ...
  - ... but *not* in parallel
- Each thread handles or manages a separate thing or task...
- But those tasks are not necessarily executing simultaneously!

# Silly Example for Threads

• Imagine the following program:

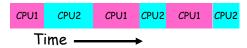
```
main() {
    ComputePI("pi.txt");
    PrintClassList("classlist.txt");
}
```

- · What is the behavior here?
- · Program would never print out class list
- Why? ComputePI would never finish

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# **Adding Threads**

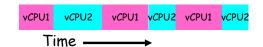
- Version of program with threads (loose syntax):
   main() {
   create\_thread(ComputePI, "pi.txt");
   create\_thread(PrintClassList, "classlist.txt");
   }
- create\_thread: Spawns a new thread running the given procedure
  - Should behave as if another CPU is running the given procedure
- Now, you would actually see the class list



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# Threads Mask I/O Latency

- A thread is in one of the following three states:
  - RUNNING running
  - READY eligible to run, but not currently running
  - BLOCKED ineligible to run
- If a thread is waiting for an I/O to finish, the OS marks it as BLOCKED
- Once the I/O finally finishes, the OS marks it as READY



# More Practical Motivation: Compute/IO overlap

Back to Jeff Dean's "Numbers Everyone Should Know"

> Handle I/O in separate thread, avoid blocking other progress

L1 cache reference	0	.5 ns
Branch mispredict	5	ns
L2 cache reference	7	ns
Mutex lock/unlock	25	ns
Main memory reference	100	ns
Compress 1K bytes with Zippy	3,000	ns
Send 2K bytes over 1 Gbps network	20,000	ns
Read 1 MB sequentially from memory	250,000	ns
Round trip within same datacenter	500,000	ns
Disk seek	10,000,000	ns
Read 1 MB sequentially from disk	20,000,000	ns
Send packet CA->Netherlands->CA	150,000,000	ns

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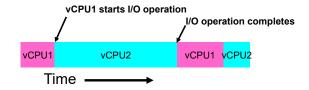
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## Threads Mask I/O Latency

• If no thread performs I/O:



• If thread 1 performs a blocking I/O operation:



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## A Better Example for Threads

- Version of program with threads (loose syntax):
   main() {
   create\_thread(ReadLargeFile, "pi.txt");
   create\_thread(RenderUserInterface);
   }
- · What is the behavior here?
  - Still respond to user input
  - While reading file in the background

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# Multithreaded Programs

- You know how to compile a C program and run the executable
  - This creates a process that is executing that program
- Initially, this new process has one thread in its own address space
  - With code, globals, etc. as specified in the executable
- · Q: How can we make a multithreaded process?
- A: Once the process starts, it issues system calls to create new threads

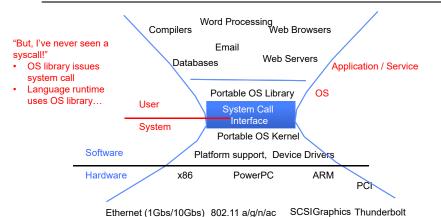
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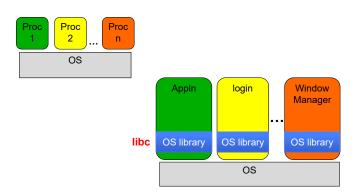
- These new threads are part of the process: they share its address space

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## System Calls ("Syscalls")



# OS Library Issues Syscalls



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## OS Library API for Threads: pthreads

Here: the "p" is for "POSIX" which is a part of a standardized API

- thread is created executing start\_routine with arg as its sole argument.
- return is implicit call to pthread exit

void pthread\_exit(void \*value\_ptr);

- terminates the thread and makes value\_ptr available to any successful join

int pthread join(pthread t thread, void \*\*value ptr);

- suspends execution of the calling thread until the target *thread* terminates.
- On return with a non-NULL value\_ptr the value passed to <u>pthread\_exit()</u> by the terminating thread is made available in the location referenced by value\_ptr.

prompt% man pthread https://pubs.opengroup.org/onlinepubs/7908799/xsh/pthread.h.html

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#### Peeking Ahead: System Call Example

• What happens when pthread create(...) is called in a process?

```
Library:
int pthread_create(...) {
    Do some work like a normal fn...

asm code ... syscall # into %eax
    put args into registers %ebx, ...
    special trap instruction

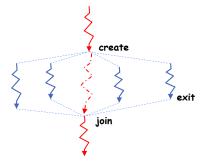
    Kernel:
        get args from regs
        dispatch to system func
        Do the work to spawn the new thread
        Store return value in %eax

get return values from regs
    Do some more work like a normal fn...
};
```

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#include <stdlib.h>

# New Idea: Fork-Join Pattern



- Main thread creates (forks) collection of sub-threads passing them args to work on...
- ... and then joins with them, collecting results.

# pThreads Example

- · How many threads are in this program?
- What function does each thread run?
- One possible result:

```
[(base) CullerMac19:code04 culler$ ./pthread 4
Main stack: 7ffee2c6b6b8, common: 10cf95048 (162)
Thread #1 stack: 70000043bef8 common: 10cf95048 (162)
Thread #3 stack: 70000041ef8 common: 10cf95048 (164)
Thread #2 stack: 70000047beef8 common: 10cf95048 (165)
Thread #8 stack: 70000047beef8 common: 10cf95048 (165)
```

- Does the main thread join with the threads in the same order that they were created?
  - · Yes: Loop calls Join in thread order
- Do the threads exit in the same order they were created?
  - No: Depends on scheduling order!
- · Would the result change if run again?
  - Yes: Depends on scheduling order!
- Is this code safe/correct???
  - No threads share are variable that is used without locking and there is a race condition!

```
#include <pthread.h>
int common = 162;
void *threadfun(void *threadid)
 long tid = (long)threadid;
 printf("Thread #%lx stack: %lx common: %l
        (unsigned long) &tid, (unsigned lo
                                                common, common++);
 pthread_exit(NULL);
 nt main (int argc, char *argv[]
   nt nthreads = 2;
    (arec > 1) (
   nthreads = atol(argv[1]);
           *threads = malloc(nthreads*sizeof(pthread t));
        (unsigned long) &t, (unsigned long) &common);
    (t=0; t<nthreads: t++){
   int rc = pthread_create(&threads[t], NULL, threadfun, (void *)t);
if (rc)(
     printf("ERROR; return code from pthread_create() is %d\n", rc);
     exit(-1);
   pthread_join(threads[t], NULL);
 pthread_exit(NULL);
                               /* last thing in the main thread */
```

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#### **Thread State**

- State shared by all threads in process/address space
  - Content of memory (global variables, heap)
  - I/O state (file descriptors, network connections, etc)
- · State "private" to each thread
  - Kept in TCB = Thread Control Block
  - CPU registers (including, program counter)
  - Execution stack what is this?
- Execution Stack

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- Parameters, temporary variables
- Return PCs are kept while called procedures are executing

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#### Shared vs. Per-Thread State

#### Shared State

State

Thread Control
Block (TCB)

Stack
Information
Saved
Registers

Thread
Metadata

----

State

Thread Control

Block (TCB)

Stack

Information

Saved

Registers

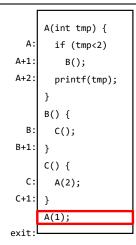
Thread

Metadata

Stack

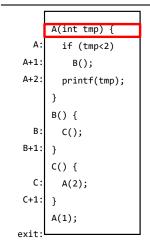
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## **Execution Stack Example**



- Stack holds temporary results
- · Permits recursive execution
- Crucial to modern languages

## **Execution Stack Example**





- Stack holds temporary results
- Permits recursive execution
- Crucial to modern languages

ared Per–Thread Per–Thread

Неар

Global Variables

Code

Stack

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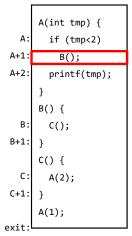
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#### A(int tmp) { if (tmp<2) A+1 B(); A+2: printf(tmp); B() { В: C(); B+1: C() { C: A(2); C+1: A(1); exit:

```
A: tmp=1
ret=exit
Pointer
```

- · Stack holds temporary results
- · Permits recursive execution
- · Crucial to modern languages

# Execution Stack Example



Stack A: tmp=1
ret=exit
Pointer

- · Stack holds temporary results
- · Permits recursive execution
- Crucial to modern languages

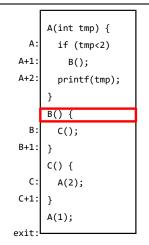
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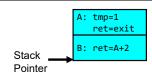
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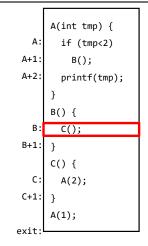
## **Execution Stack Example**

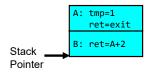




- · Stack holds temporary results
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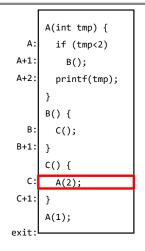
# **Execution Stack Example**



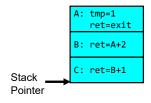


- Stack holds temporary results
- Permits recursive execution
- Crucial to modern languages

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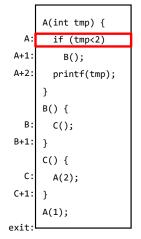


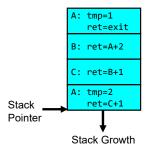
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- · Stack holds temporary results
- · Permits recursive execution
- · Crucial to modern languages

# **Execution Stack Example**





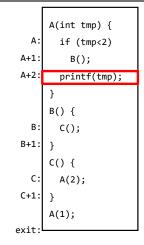
- · Stack holds temporary results
- · Permits recursive execution
- Crucial to modern languages

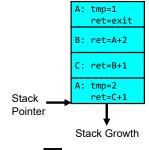
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# **Execution Stack Example**

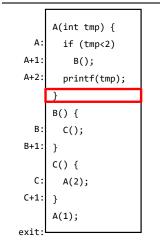


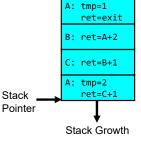


#### Output: >2

- · Stack holds temporary results
- · Permits recursive execution
- Crucial to modern languages

#### **Execution Stack Example**

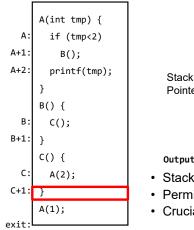


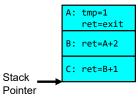


#### Output: >2

- · Stack holds temporary results
- Permits recursive execution
- · Crucial to modern languages

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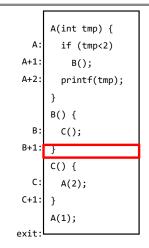


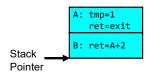
#### Output: >2

- · Stack holds temporary results
- · Permits recursive execution
- · Crucial to modern languages

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## **Execution Stack Example**





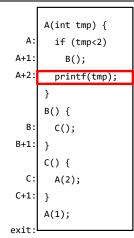
#### Output: >2

- · Stack holds temporary results
- · Permits recursive execution
- · Crucial to modern languages

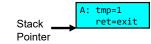
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# **Execution Stack Example**



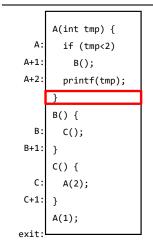
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#### Output: >2 1

- · Stack holds temporary results
- · Permits recursive execution
- · Crucial to modern languages

## **Execution Stack Example**





#### Output: >2 1 · Stack holds temporary results

- · Permits recursive execution
- Crucial to modern languages

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```
A(int tmp) {
 if (tmp<2)
    B();
 printf(tmp);
B() {
 C();
C() {
 A(2);
A(1);
```

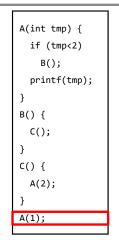
#### Output: >2 1

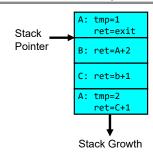
- · Stack holds temporary results
- · Permits recursive execution
- · Crucial to modern languages

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## **Execution Stack Example**

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- · Stack holds temporary results
- · Permits recursive execution
- Crucial to modern languages

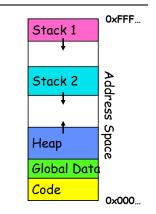
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# Memory Layout with Two Threads

- · Two sets of CPU registers
- · Two sets of Stacks
- · Issues:

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- How do we position stacks relative to each other?
- What maximum size should we choose for the stacks?
- What happens if threads violate this?
- How might you catch violations?

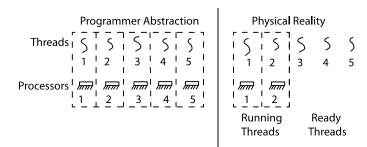


INTERLEAVING AND NONDETERMINISM (The beginning of a long discussion!)

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#### **Thread Abstraction**



- Illusion: Infinite number of processors
- · Reality: Threads execute with variable "speed"
  - Programs must be designed to work with any schedule

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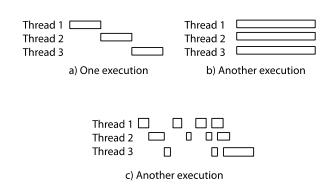
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# Programmer vs. Processor View

Programmer's View	Possible Execution #1	Possible Execution #2	Possible Execution #3
		•	•
•		•	•
x = x + 1;	x = x + 1;	x = x + 1	x = x + 1
y = y + x;	y = y + x;		y = y + x
z = x + 5y;	z = x + 5y;	thread is suspended	•••••
		other thread(s) run	thread is suspended
		thread is resumed	other thread(s) run
		***************************************	thread is resumed
		y = y + x	•••••
		z = x + 5y	z = x + 5y

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# Possible Executions



## **Correctness with Concurrent Threads**

- Non-determinism:
  - Scheduler can run threads in any order
  - Scheduler can switch threads at any time
  - This can make testing very difficult
- Independent Threads
  - No state shared with other threads
  - Deterministic, reproducible conditions
- Cooperating Threads
  - Shared state between multiple threads
- · Goal: Correctness by Design

# Race Conditions: Example 1

• Initially x == 0 and y == 0

Thread A	Thread	
x = 1;	y = 2;	

- What are the possible values of x below after all threads finish?
- Must be 1. Thread B does not interfere

## Race Conditions: Example 2

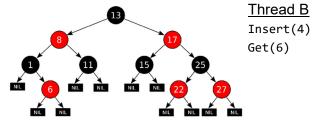
• Initially x == 0 and y == 0

- What are the possible values of x below?
- 1 or 3 or 5 (non-deterministically)
- Race Condition: Thread A races against Thread B!

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# Example: Shared Data Structure

Thread A Insert(3)



Tree-Based Set Data Structure

## **Relevant Definitions**

- Synchronization: Coordination among threads, usually regarding shared data
- Mutual Exclusion: Ensuring only one thread does a particular thing at a time (one thread excludes the others)
  - Type of synchronization
- Critical Section: Code exactly one thread can execute at once
  - Result of mutual exclusion
- · Lock: An object only one thread can hold at a time
  - Provides mutual exclusion

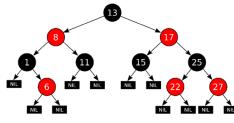
#### Locks

- · Locks provide two atomic operations:
  - Lock.acquire() wait until lock is free; then mark it as busy
    - » After this returns, we say the calling thread holds the lock
  - Lock.release() mark lock as free
    - » Should only be called by a thread that currently holds the lock
    - » After this returns, the calling thread no longer holds the lock
- For now, don't worry about how to implement locks!
  - We'll cover that in substantial depth later on in the class

#### Thread A

#### Insert(3)

- Lock.acquire()
- Insert 3 into the data structure
- Lock.release()



#### Tree-Based Set Data Structure

#### Thread B

#### Insert(4)

- Lock.acquire()
- Insert 4 into the data structure
- Lock.release()

#### Get(6)

- Lock.acquire()
- Check for membership
- Lock.release()

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# OS Library Locks: pthreads

You'll get a chance to use these in Homework 1

#### Our Example

#### Recall: UNIX System Structure

User Mode		Applications	(the users)	
Oser Mode			shells and commands mpilers and interpreters system libraries	1
		syster	m-call interface to the ke	ernel
Kernel Mode	Kernel	signals terminal handling character I/O system terminal drivers	file system swapping block I/O system disk and tape drivers	CPU scheduling page replacement demand paging virtual memory
		kernel interface to the hardware		
Hardware		terminal controllers terminals	device controllers disks and tapes	memory controllers physical memory

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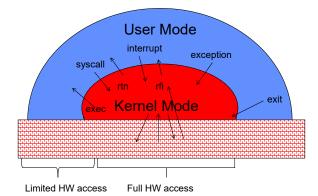
# 3 types of Kernel Mode Transfer

- Syscall
  - Process requests a system service, e.g., exit
  - Like a function call, but "outside" the process
  - Does not have the address of the system function to call
  - Like a Remote Procedure Call (RPC) for later
  - Marshall the syscall id and args in registers and exec syscall
- Interrupt
  - External asynchronous event triggers context switch
  - eg. Timer, I/O device
  - Independent of user process
- · Trap or Exception
  - Internal synchronous event in process triggers context switch
  - e.g., Protection violation (segmentation fault), Divide by zero,

# Implementing Safe Kernel Mode Transfers

- Important aspects:
  - Controlled transfer into kernel (e.g., syscall table)
  - Separate kernel stack!
- · Carefully constructed kernel code packs up the user process state and sets it aside
  - Details depend on the machine architecture
  - More on this next time
- · Should be impossible for buggy or malicious user program to cause the kernel to corrupt itself!

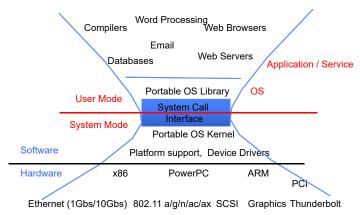
Recall: Life of a Process



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#### Recall: System Call Interface: A Narrow Waist



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Hardware support: Interrupt Control

- Interrupt processing not visible to the user process:
  - Occurs between instructions, restarted transparently
  - No change to process state

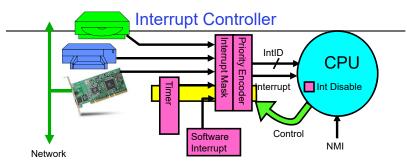
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- What can be observed even with perfect interrupt processing?
- Interrupt Handler invoked with interrupts 'disabled'
  - Re-enabled upon completion
  - Non-blocking (run to completion, no waits)
  - Pack up in a queue and pass off to an OS thread for hard workwake up an existing OS thread

# Kernel System Call Handler

- · Vector through well-defined syscall entry points!
  - Table mapping system call number to handler
- Locate arguments
  - In registers or on user (!) stack
- · Copy arguments
  - From user memory into kernel memory
  - Protect kernel from malicious code evading checks
- Validate arguments
  - Protect kernel from errors in user code
- · Copy results back
  - Into user memory

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- · Interrupts invoked with interrupt lines from devices
- · Interrupt controller chooses interrupt request to honor
  - Interrupt identity specified with ID line
  - Mask enables/disables interrupts
  - Priority encoder picks highest enabled interrupt
  - Software Interrupt Set/Cleared by Software
- CPU can disable all interrupts with internal flag
- · Non-Maskable Interrupt line (NMI) can't be disabled

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# How do we take interrupts safely?

- · Interrupt vector
  - Limited number of entry points into kernel
- · Kernel interrupt stack
  - Handler works regardless of state of user code
- · Interrupt masking

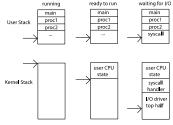
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- Handler is non-blocking
- · Atomic transfer of control
  - "Single instruction"-like to change:
    - » Program counter
    - » Stack pointer
    - » Memory protection
    - » Kernel/user mode
- · Transparent restartable execution
  - User program does not know interrupt occurred

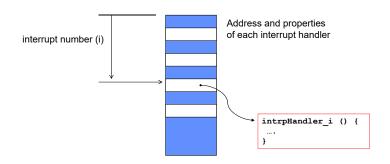
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# Need for Separate Kernel Stacks

- · Kernel needs space to work
- Cannot put anything on the user stack (Why?)
- Two-stack model
  - OS thread has interrupt stack (located in kernel memory) plus User stack (located in user memory)
  - Syscall handler copies user args to kernel space before invoking specific function (e.g., open)
  - Interrupts (???)



## Interrupt Vector

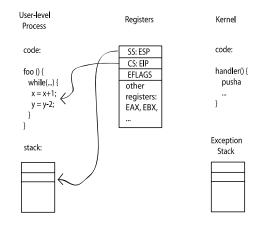


- · Where else do you see this dispatch pattern?
  - System Call
  - Exceptions

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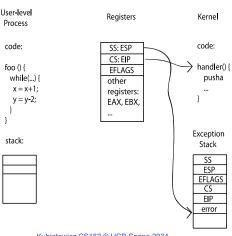
#### **Before**



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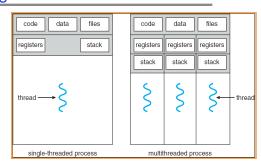
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# **During Interrupt/System Call**



## **Managing Processes**

- · How to manage process state?
  - How to create a process?
  - How to exit from a process?
- Remember: Everything outside of the kernel is running in a process!
  - Including the shell! (Homework 2)
- Processes are created and managed... by processes!



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# Bootstrapping

- If processes are created by other processes, how does the first process start?
- · First process is started by the kernel
  - Often configured as an argument to the kernel before the kernel boots
  - Often called the "init" process
- After this, all processes on the system are created by other processes

## Next time: Process Management API

- exit terminate a process
- fork copy the current process
- exec change the *program* being run by the current process
- wait wait for a process to finish
- kill send a signal (interrupt-like notification) to another process
- sigaction set handlers for signals

## Conclusion

- Threads are the OS unit of concurrency
  - Abstraction of a virtual CPU core
  - Can use pthread\_create, etc., to manage threads within a process
  - They share data  $\rightarrow$  need synchronization to avoid data races
- Processes consist of one or more threads in an address space
  - Abstraction of the machine: execution environment for a program
  - Can use fork, exec, etc. to manage threads within a process
- We saw the role of the OS library
  - Provide API to programs
  - Interface with the OS to request services

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