Better Embedded System SW

Companion blog to the book Better Embedded System Software by Phil Koopman at Carnegie Mellon University

Friday, October 3, 2014

A Case Study of Toyota Unintended Acceleration and Software Safety

Oct 3, 2014: updated with video of the lecture

Here is my case study talk on the Toyota unintended acceleration cases that have been in the news and the courts the past few years.

The talk summary is below and embedded slides are below. Additional pointers:

- · Vimeo hosted video (higher quality source file)
- · Youtube hosted video
- Streaming video of talk (1 hour split screen with speaker & slides, requires free account)
- Download Slides
- · Slideshare hosted copy of slides

(Please see end of post for video download and copyright info.)

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A Case Study of Toyota Unintended Acceleration and Software Safety

Abstract

Investigations into potential causes of Unintended Acceleration (UA) for Toyota vehicles have made news several times in the past few years. Some blame has been placed on floor mats and sticky throttle pedals. But, a jury trial verdict was based on expert opinions that defects in Toyota's Electronic Throttle Control System (ETCS) software and safety architecture caused a fatal mishap.

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About Me



Phil Koopman

I work with self-driving car safety and more generally with dependable embedded systems. I teach at Carnegie

Mellon University.

As with any blog, these posts often contain speculative and partially formed thoughts, and should not be interpreted as a fully considered opinion unless stated otherwise.

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Key pages:

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Safety Culture

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This talk will outline key events in the still-ongoing Toyota UA litigation process, and pull together the technical issues that were discovered by NASA and other experts. The results paint a picture that should inform future designers of safety critical software in automobiles and other systems.

Bio:

Prof. Philip Koopman has served as a Plaintiff expert witness on numerous cases in Toyota Unintended Acceleration litigation, and testified in the 2013 Bookout trial. Dr. Koopman is a member of the ECE faculty at Carnegie Mellon University, where he has worked in the broad areas of wearable computers, software robustness, embedded networking, dependable embedded computer systems, and autonomous vehicle safety. Previously, he was a submarine officer in the US Navy, an embedded CPU architect for Harris Semiconductor, and an embedded system researcher at United Technologies. He is a senior member of IEEE, senior member of the ACM, and a member of IFIP WG 10.4 on Dependable Computing and Fault Tolerance. He has affiliations with the Carnegie Mellon Institute for Software Research (ISR) and the National Robotics Engineering Center (NREC).

I am getting an increasing number of requests to do this talk in person, both as a keynote speaker and for internal corporate audiences. Audiences tell me that while the video is nice, an in-person experience of both the presentation and small-group follow-up discussions has a lot more impact for organizations who need help in coming to terms with creating high quality software and safety critical systems. If you are interested please get in touch for details: koopman@cmu.edu

Other info:

- Download copy of full-resolution video file set of talk, Box.com 340 MB .zip file of a web
 directory with interactive split-screen viewing format. Experts only! Please do not ask me
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- Download medium-bit-rate 720p video from CMU server (.mp4; 124MB)

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Cornegie Mellon

A Case Study of Toyota Unintended Acceleration and Software Safety

Prof. Phil Koopman

September 18, 2014
Carnegie Mellon University koopman@cmu.edu betterembsw.blogspot.com







at October 03, 2014





Labels: safety, Toyota UA

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kredit agya November 11, 2014 at 2:38 PM

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Phil Koopman November 11, 2014 at 9:39 PM

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Reply

Karim Naqvi September 11, 2015 at 1:37 PM

Wonderful, Phil! I had not noticed you posted this presentation. I'll point students in my embedded class to the video, and of course to your text which, unfortunately, I'm not using this fall. The presentation is a bit of a challenge: fairly dense slides, with much jargon. Still, a great resource, and thank you.

Reply



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Please send me your comments. I read all of them, and I appreciate them. To control spam I manually approve comments before they show up. It might take a while to respond. I appreciate generic "I like this post" comments, but I don't publish non-substantive comments like that.

If you prefer, or want a personal response, you can send e-mail to comments@koopman.us. If you want a personal response please make sure to include your e-mail reply address. Thanks!

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Static Analysis Ranked Defect List

Crazy idea of the day: Static Analysis Ranked Defect List. Here is a software analysis tool feature request/product idea: So many times we...



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Don't use macros for MIN and MAX



It is common to see small helper functions implemented as macros, especially in older C code. Everyone seems to do it. But you should ...



What's the best CRC polynomial to use?

(If you want to know more, see my Webinar on CRCs and checksums based on work sponsored by the FAA.) If you are looking for a lightwei...

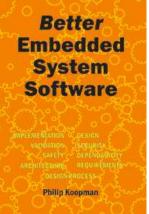


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