# Index Files and B+Tree Refinements

R & G - Chapter 9-10



#### General characteristics of an index: An Outline

- Issues to consider in any index structure (not just B+-trees)
  - Query support: what class of queries does the index allow?
  - Choice of Search Key
    - Affects the queries for which we can use an index.
  - Data Entry Storage
    - Affects performance of the index
  - Variable-length key tricks
    - Affects performance of the index
  - Cost Model for Index vs Heap vs Sorted File







#### **Indexes: Basic Selection**

- **Basic Selection:** <key> <op> <constant>
  - Equality selections (op is =)
  - Range selections (op is one of <, >, <=, >=, BETWEEN)
  - B+-trees provide both
  - Linear Hash indexes provide only equality (but are interesting!)



#### **Indexes: Other Selections**

#### More Exotic Selections:

- 2-d box (current map boundaries)
- 2-d circle ("within 2 miles of Empire State Building")
- Common **n-dimensional indexes**: <u>R-tree</u>, <u>KD-tree</u>, etc.
  - Beware of the curse of dimensionality
- Near-neighbor queries ("10 restaurants closest to Empire State Building")
- Regular expression matches, genome string matches, etc.
- See Postgres' <u>GiST</u> indexes for a flexible structure developed at Berkeley





### For Today

- In the remainder of our discussion, we'll focus on traditional 1-d range search
  - And equality as a special case
  - As in B+-trees



- Can index on any ordered subset of columns. Order matters!
  - Determines the queries supported
- In an ordered index (e.g. B+-tree) the keys are ordered **lexicographically** by the search key columns:
  - Ordered by the 1<sup>st</sup> column
  - 2 items match on 1<sup>st</sup> column? Ordered by 2<sup>nd</sup>
  - Match on 1<sup>st</sup> and 2<sup>nd</sup> column? Ordered by 3<sup>rd</sup>
  - Etc.
- E.g. table to right ordered lexicographically by the search key <Age, Salary>

SSN	Last Name	First Name	Age	Salary
123	Adams	Elmo	31	\$300
443	Grouch	Oscar	32	\$400
244	Oz	Bert	55	\$140
134	Sanders	Ernie	55	\$400

- Defn: A **composite search key** on columns  $(k_1, k_2, ..., k_n)$  "matches" a query if:
  - The query is a *conjunction* of *m* >= 0 equality clauses of the form: k<sub>1</sub> = <val<sub>1</sub>> AND k<sub>2</sub> = <val<sub>2</sub>> AND .. AND k<sub>m</sub> = <val<sub>m</sub>> and at most 1 additional *range* clause of the form: AND k<sub>m+1</sub> op <val>, where op is one of {<, >}
- Why does this "match"? Lookup and scan in lexicographic order
  - Can do a lookup on equality conjuncts to find start-of-range
  - Can do a scan of contiguous data entries at leaves
    - satisfy the m+1<sup>st</sup> conjunct
    - or if there is no m+1<sup>st</sup> conjunct
      - scan the entire set of matches to the first m conjuncts



- **Composite Keys:** more than one column
  - Lexicographic order
  - Search a range?
  - <Age, Salary>
- Legend

Green for rows we visit that are in the range

Red for rows we visit that are not in the range

SSN	Last Name	First Name	Age	Salary
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- Composite Keys: more than one column
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  - <Age, Salary>:
    - Age = 31 & Salary = 400

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- Composite Keys: more than one column
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  - Search a range?
  - <Age, Salary>:
  - Age = 31 & Salary = 400
    - Age = 55 & Salary > 200

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### Search Key and Ordering, Pt 6, cont

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  - Lexicographic order
  - Search a range?
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  - Age = 55 & Salary > 200
    - Age > 31 & Salary = 400

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  - Age > 31
    - Salary = 300

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# Data Entry Storage Intro

- What is the representation of data in the index?
  - Actual data or pointer to the data
- How is the data stored in the data file?
  - Clustered or unclustered with respect to the index

#### Big Impact on Performance

• We'll learn each of these next



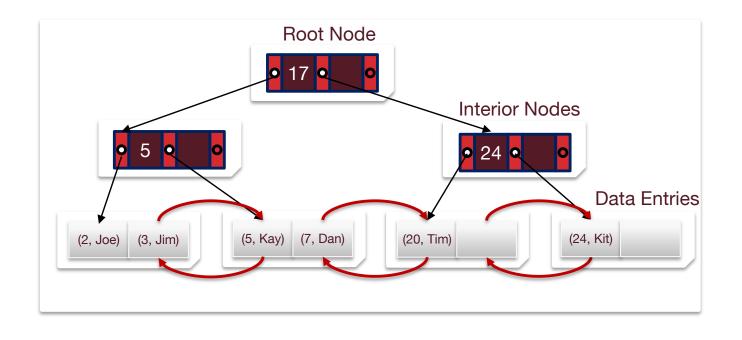
#### Three basic alternatives for data entries in any index

- Three basic alternatives for data entries in any index
  - Alternative 1: By Value
  - Alternative 2: By Reference
  - Alternative 3: By List of references
    - We'll look in the context of B+-trees, but applies to any index



#### Alternative 1 Index (B+ Tree)

- Record contents are stored in the index file
  - No need to follow pointers

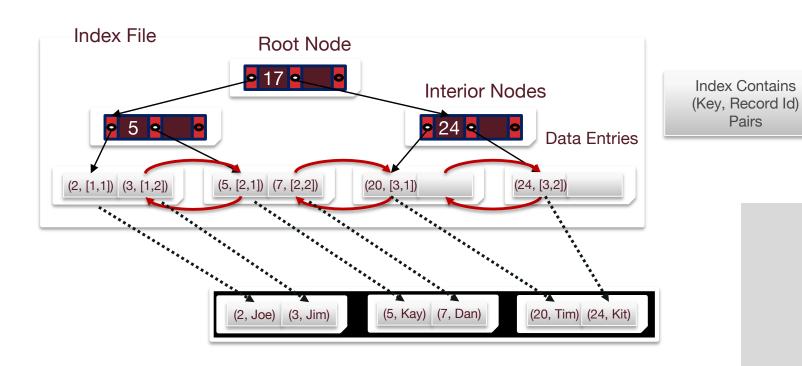


uid	name
2	Joe
3	Jim
5	Кау
7	Dan
20	Tim
24	Kit

#### Alternative 2 Index

• We used in slides above

Alternative 2: By Reference, <k, rid of matching data record> ullet

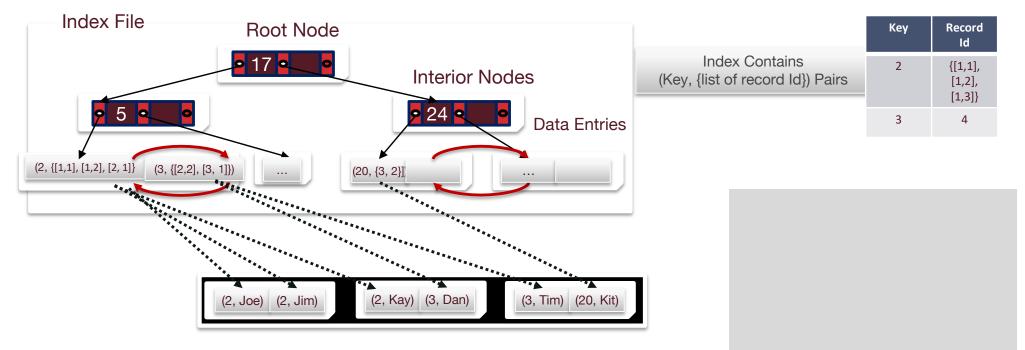


uid name 2 Joe 3 Jim 5 Kay 7 Dan 20 Tim 24 Kit

Pairs

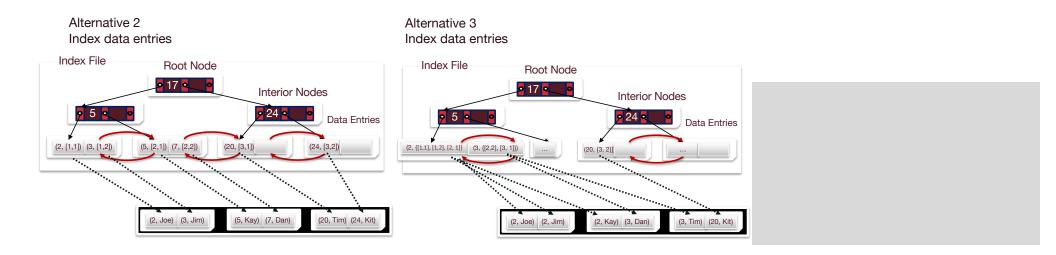
#### Alternative 3 Index

- Alternative 3: **By List of references,** <**k**, list of rids of matching data records>
  - Alternative 3 more compact than alternative 2
    - For very large rid lists, single data entry spans multiple blocks



# Indexing By Reference

- Both Alternative 2 and Alternative 3 index data by reference
- By-reference is *required* to support multiple indexes per table
  - Otherwise we would be replicating entire tuples
  - Replicating data leads to complexity when we're doing updates, so it's something we want to avoid



#### Alternative 2 vs Alternative 3 Table Illustration

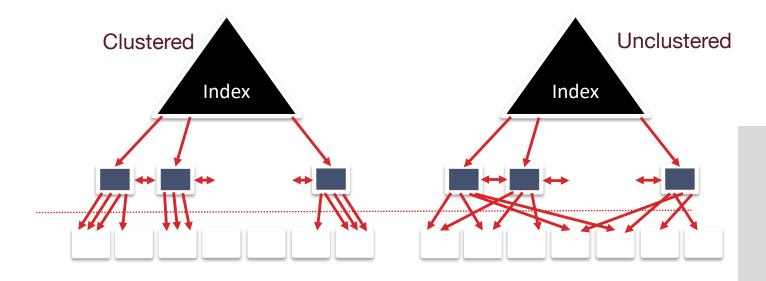
Alternative : ndex data								Alternative 3	
Кеу	Record Id		SSN	Last Name	First Name	Salary		Index data Key	entries Record Id
Gonzalez	[3, 1]	$\longrightarrow$	123	Gonzalez	Amanda	\$400	*	Gonzalez	[3, {1, 2, 3}]
Gonzalez	[3, 2]		443	Gonzalez	Joey	\$300	$\rightarrow$	Hong	[3,4]
Gonzalez	[3, 3]		244	Gonzalez	Jose	\$140			
Hong	[3, 4]	<b></b>	134	Hong	Sue	\$400			

#### Clustered vs. Unclustered Index

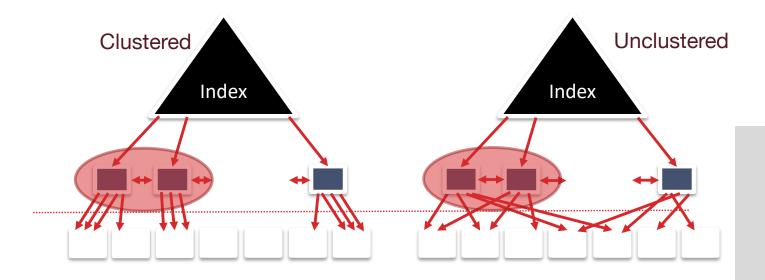
- By-reference indexes (Alt 2 and 3) can be *clustered* or *unclustered* 
  - Really this is a property of the heap file associated with the index!
- Clustered index:
  - Heap file records are kept mostly ordered according to **search keys** in index
    - Heap file order need not be perfect: this is just a performance hint
    - Cost of retrieving data records through index varies greatly based on whether index is clustered or not!
- Note: different definition of "clustering" in AI:
  - grouping nearby items in *n*-space



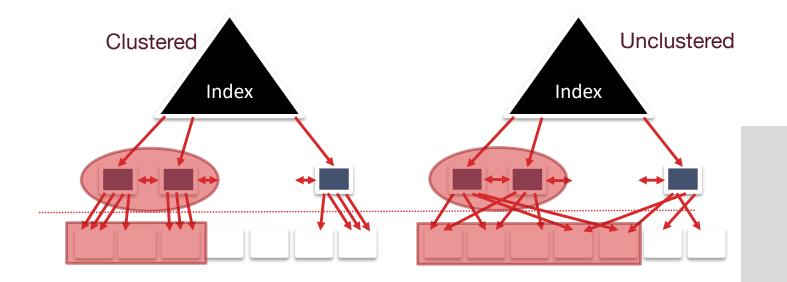
- To build a clustered index, first sort the heap file
  - Leave some free space on each block for future inserts
  - Index entries direct search for data entries



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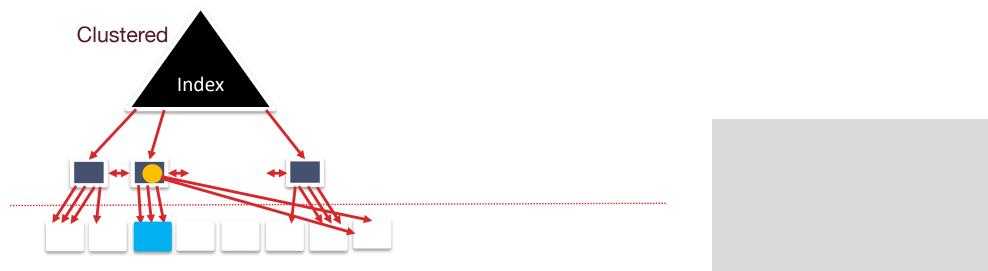
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- To build a clustered index, first sort the heap file
  - Leave some free space on each block for future inserts
- Blocks at end of file may be needed for inserts
  - Order of data records is "close to", but not identical to, the sort order



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#### Clustered vs. Unclustered Indexes Pros

- Clustered Index Pros
  - Efficient for range searches
  - Potential locality benefits
    - Sequential disk access, prefetching, etc.
  - Support certain types of compression
    - More soon on this topic



### Clustered vs. Unclustered Indexes Cons

- Clustered Cons
  - More expensive to maintain
    - Need to periodically update heap file order
    - Solution: on the fly or "lazily" via reorganizations
  - Heap file usually only **packed to 2/3** to accommodate inserts



### **B+TREE REFINEMENT:** VARIABLE-LENGTH KEYS



## Variable Length Keys & Records

• So far we have been using integer keys



What would happen to our occupancy invariant with variable length keys?



## **Redefine Occupancy Invariant**

- Order (d) makes little sense with variable-length entries
  - Different nodes have different numbers of entries.
  - Index pages often hold many more entries than leaf pages
  - Even with fixed length fields, Alternative 3 gives variable length data entries
- Use a physical criterion in practice: at-least half-full
  - Measured in bytes
- Many real systems are even sloppier than this
  - Only reclaim space when a page is completely empty.
  - Basically the deletion policy we described above...



## Prefix Compress Keys?

• How can we get more keys on a page?



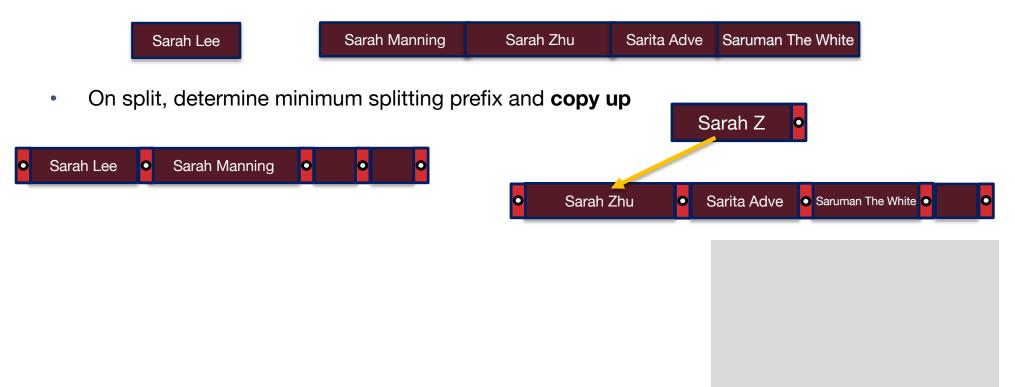
• Dan • Dani • Dav • Davi • Di • • • • • • •

• Are these the same

- David Jones?
- Not the same partitioning of possible keys
- But why would we care??

# **Prefix Key Compression**

• What if we compress starting at leaf:

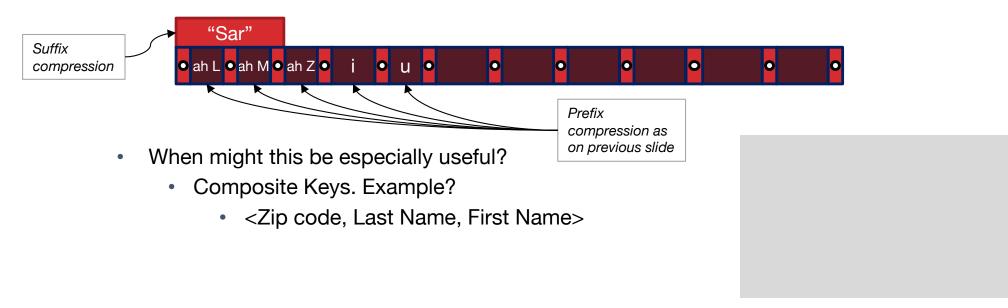


# Suffix Key Compression

All keys have large common prefix



• Move common prefix to header, leave only (compressed) suffix next to pointer



#### **B+-TREE COSTS**



# **Recall: Cost of Operations**

	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D
Insert	2*D	((log <sub>2</sub> B) + B)*D
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D

- Can we do better with indexes?
- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block



## **Cost of Operations**

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
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#### Can we do better with indexes?

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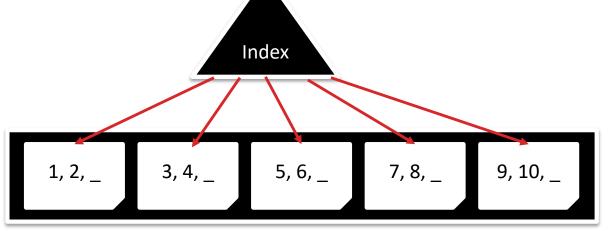
## Cost of Operations, cont

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- **B:** The number of data blocks
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#### Clustered vs. Unclustered Index Assumptions

- Store data by reference (Alternative 2)
- Clustered index with 2/3 full heap file pages
  - Clustered → Heap file is initially sorted
  - Fan-out (F): relatively large. Why?
    - Page of <key, pointer> pairs ~ O(R)
  - Assume static index

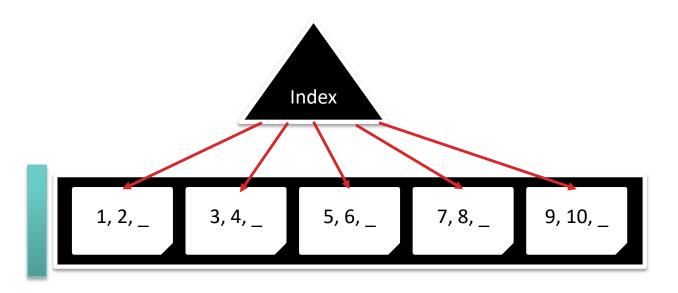


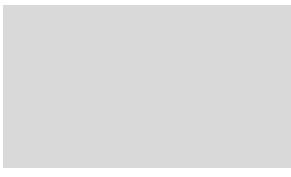


#### Scan all the Records

- Do we need an Index?
  - No
- Cost? = 1.5 \* B \* D
  - Why?

Recall assumption from before regarding clustered indexes: heap file pages only **2/3** full.





## Cost of Operations: Scan

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	((log <sub>2</sub> B) + B)*D	
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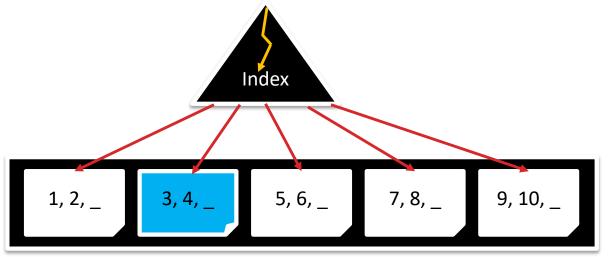
## Cost of Operations: Equality Search?

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	((log <sub>2</sub> B) + B)*D	
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D	

- **B:** The number of data blocks
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- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

#### Find the record with key 3, pt 1

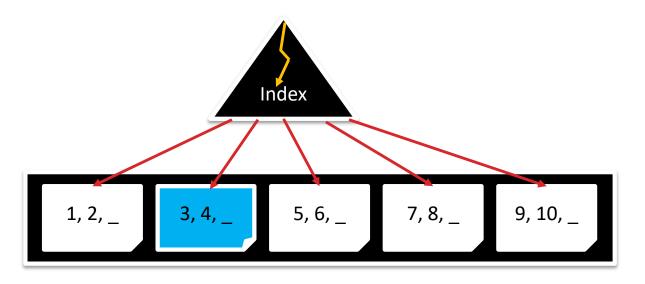
- Search the index:=  $(\log_F (BR/E) + 1) * D$ 
  - BR is the total number of records; E is the #records per leaf
  - the +1 is an "off by 1" thing: catches the cost of the root
  - E.g. F = 4, BR/E = 16: root, intermediate, leaf levels.
  - Log<sub>4</sub>(16) = 2, and I/O cost is 3!





### Find the record with key 3, pt 2

- Search the index:=  $(\log_F (BR/E) + 1) * D$
- Lookup record in heap file by record-id = 1 \* D
  - Recall record-id = <page, slot #>





## Cost of Operations: Equality Search

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	(log <sub>F</sub> (BR/E)+2)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)^*D$	
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D	

- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block
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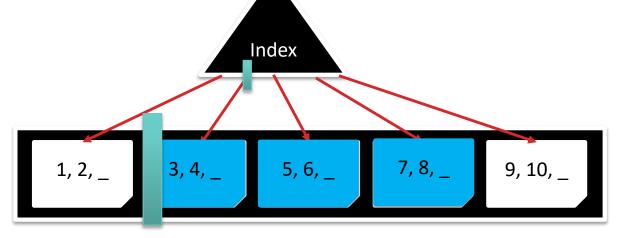
## Cost of Operations: Range Search?

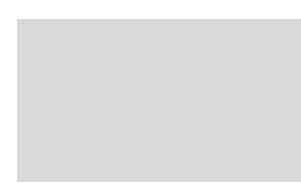
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Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	(log <sub>F</sub> (BR/E)+2)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)^*D$	
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D	

- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

## Find keys between 3 and 7

- Search the index: =  $(\log_F (BR/E) + 1) * D$
- Scan the leaf level and lookup each matching record in the heap file by record-id
  - Recall record-id = <page, slot #>
- Heap file access: (3/2 \* #pages) \* D
- Scanning the leaf level is similar to heap file access: assume same (3/2 \* #pages) \* D
- In total (log<sub>F</sub> (BR/E) + 3 \* # pages) \* D since one leaf page is overcounted in searching index and scanning leaf level





## Cost of Operations: Range Search

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	(log <sub>F</sub> (BR/E)+2)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	(log <sub>F</sub> (BR/E)+3*pages)*D
Insert	2*D	((log <sub>2</sub> B) + B)*D	
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- **B:** The number of data blocks
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- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

## Cost of Operations: Insert?

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	(log <sub>F</sub> (BR/E)+2)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	(log <sub>F</sub> (BR/E)+3*pages)*D
Insert	2*D	((log <sub>2</sub> B) + B)*D	
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D	

- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

## **Cost of Operations: Insert**

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	(log <sub>F</sub> (BR/E)+2)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	(log <sub>F</sub> (BR/E)+3*pages)*D
Insert	2*D	((log <sub>2</sub> B) + B)*D	(log <sub>F</sub> (BR/E)+4)*D
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D	

- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

## Cost of Operations: Delete

Why "+4" in Insert/Delete?

	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	3/2 * B * D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	(log <sub>F</sub> (BR/E)+2)*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	(log <sub>F</sub> (BR/E)+3*pages)*D
Insert	2*D	((log <sub>2</sub> B) + B)*D	(log <sub>F</sub> (BR/E)+4)*D
Delete	(0.5*B+1)*D	((log <sub>2</sub> B) + B)*D	(log <sub>F</sub> (BR/E)+4)*D

- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

## Cost of Operations: Big O Notation

	Heap File	Sorted File	Clustered Index
Scan all records	O(B)	O(B)	O(B)
Equality Search	O(B)	O(log <sub>2</sub> B)	O(log <sub>F</sub> B)
Range Search	O(B)	O(log <sub>2</sub> B)	O(log <sub>F</sub> B)
Insert	O(1)	O(B)	O(log <sub>F</sub> B)
Delete	O(B)	O(B)	O(log <sub>F</sub> B)

- **B:** The number of data blocks
- **R:** Number of records per block
- **D:** Average time to read/write disk block
- **F:** Average internal node fanout
- E: Average # data entries per leaf

### **Constant factors**

- Assume you can do 100 sequential I/Os in the time of 1 random I/O
- For a particular lookup, is a B+-tree better than a full-table scan?
  - Had better be very "selective"
    - Visit < ~1% of pages!
  - Or do mostly sequential I/O at leaf level
    - Clustered index
  - Or use SSD
    - SSDs make indexes attractive
    - Especially for read-mostly workloads



# Summary

- Query Structure
  - Understand composite search keys
  - Lexicographic order and search key prefixes
- Data Storage
  - Data Entries: Alt 1 (tuples), Alt 2 (recordIds), Alt 3 (lists of recordIds)
  - Clustered vs. Unclustered
    - Only Alt 2 & 3!



# Summary Cont

- Variable length key refinements
  - Fill factors for variable-length keys
  - Prefix and suffix key compression
- B+-tree Cost Model
  - Attractive big-O
  - Don't forget constant factors of random I/O
    - Hard to beat sequential I/O of scans unless very selective
  - Indexes beyond B+-trees for more complex searches